

FIG. 1 is a block diagram of a system 10 for controlling a robotic arm 20. The system 10 includes a computer 12, a database 14, a server 16, and a control unit 22. The computer 12 is connected to the database 14 and the server 16. The server 16 is connected to the control unit 22, which is connected to the robotic arm 20. The control unit 22 also includes a monitor 24.

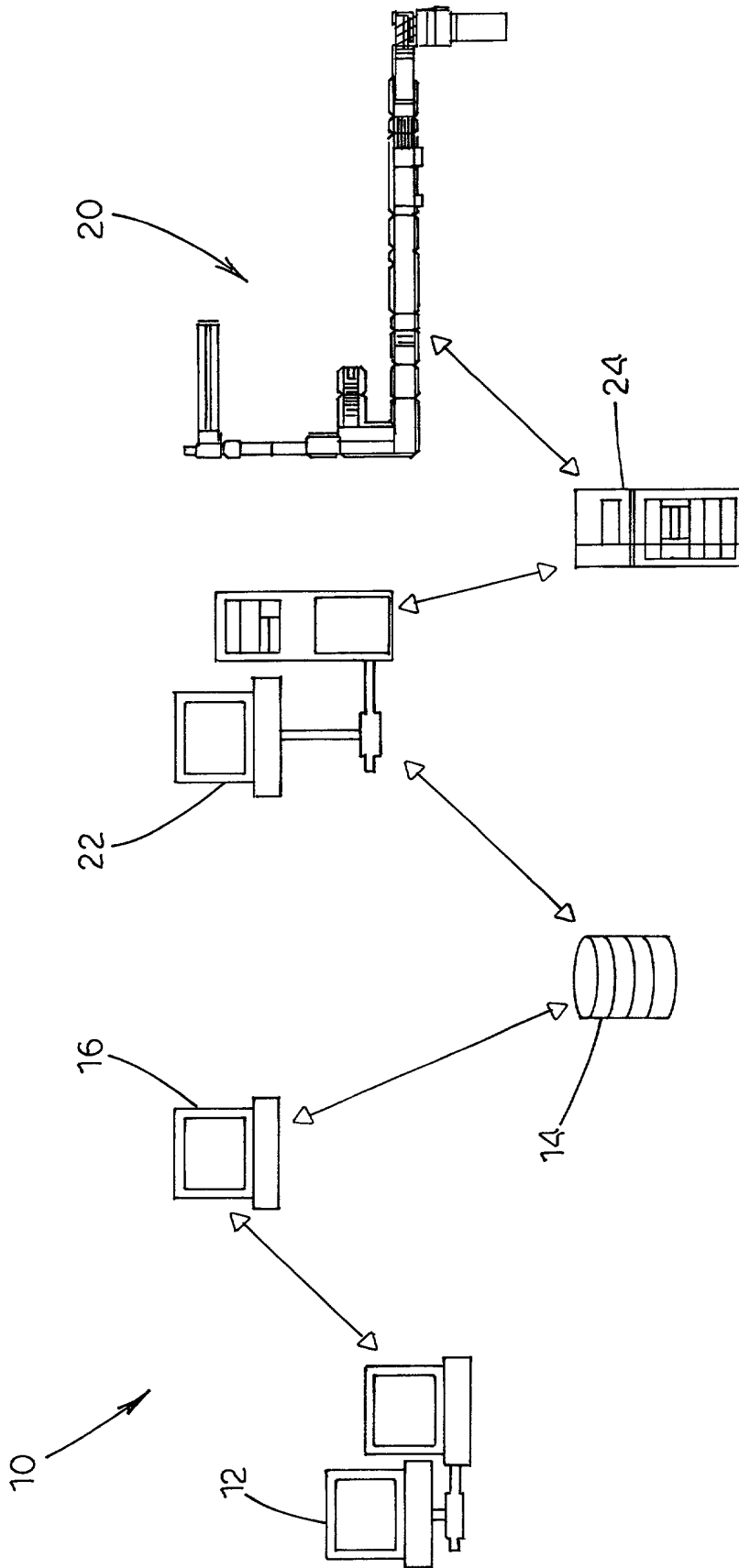
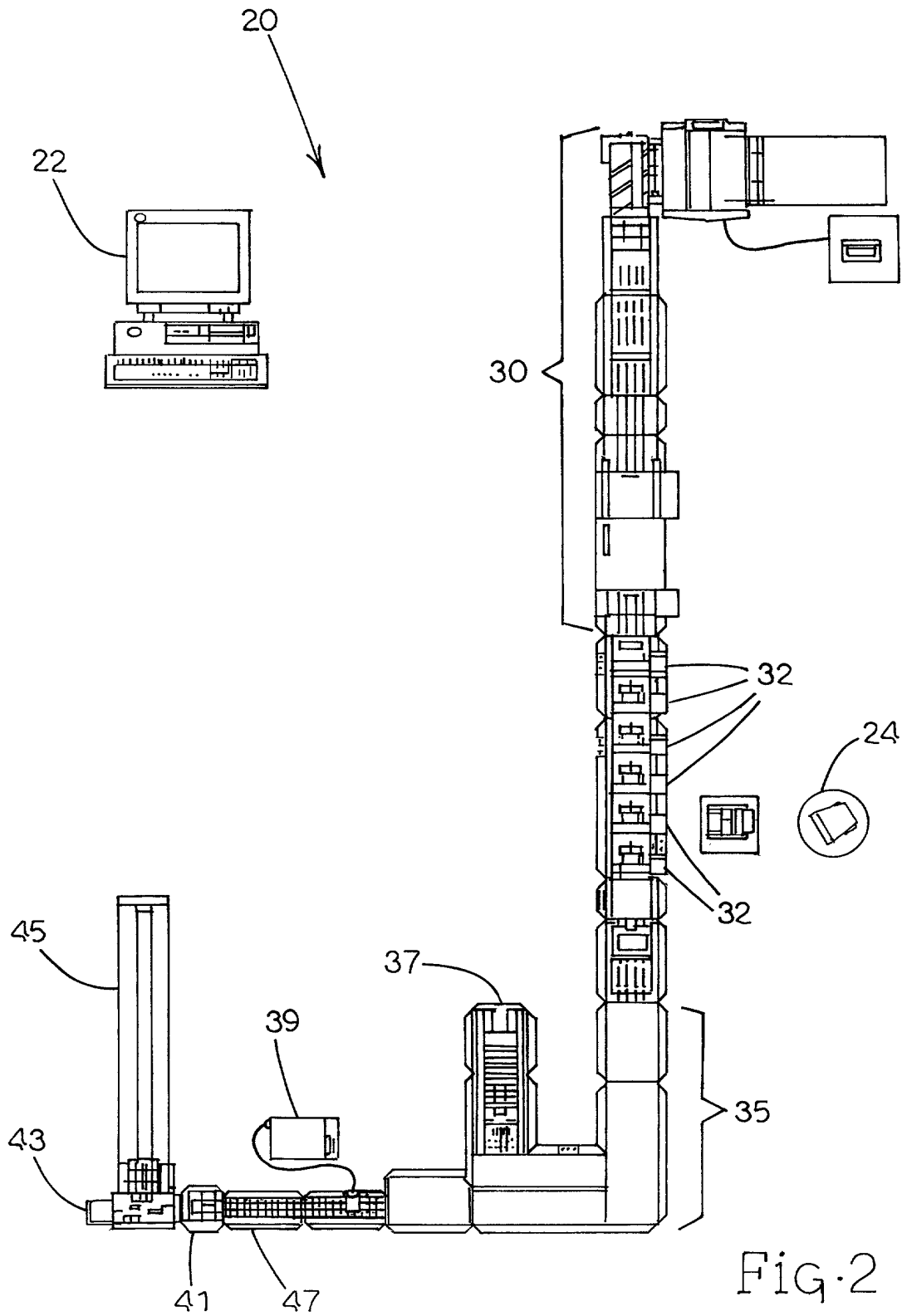


Fig. 1



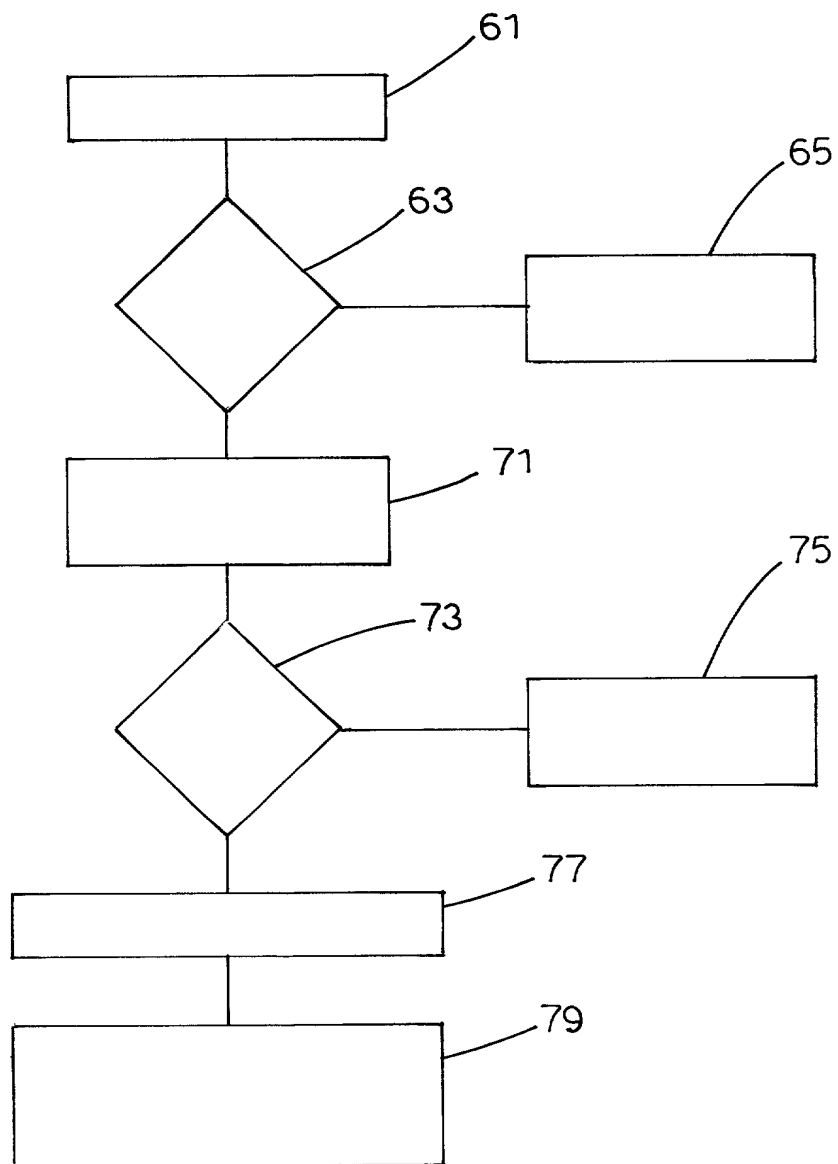


Fig. 3

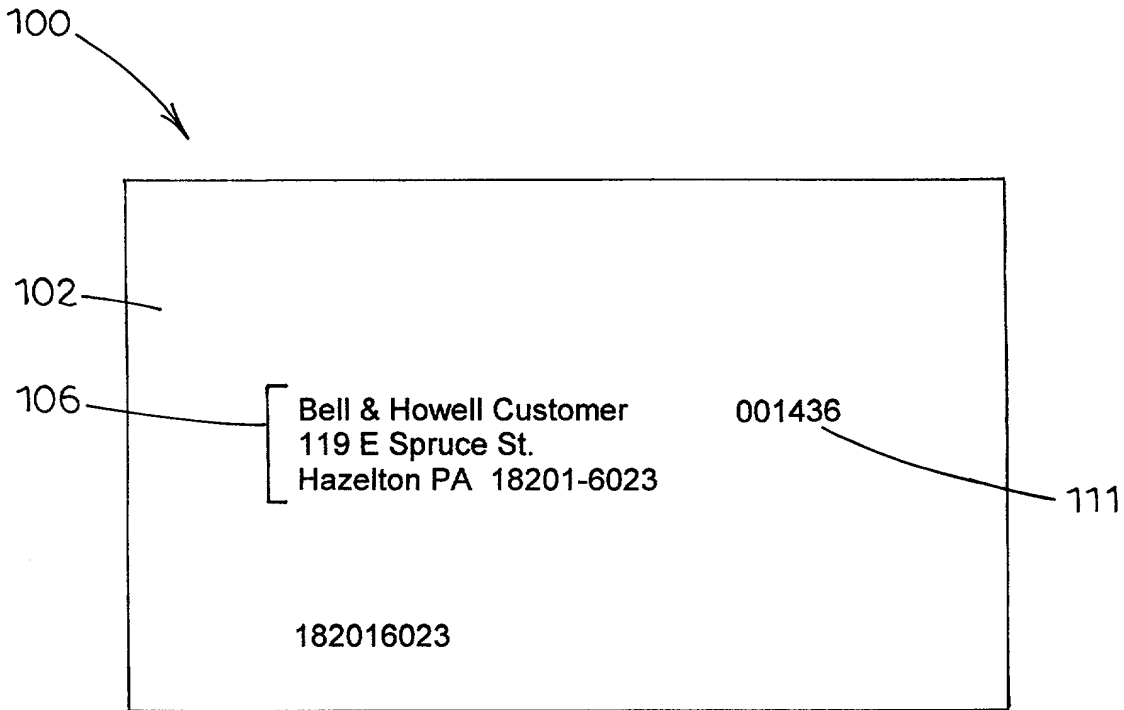


Fig. 4A

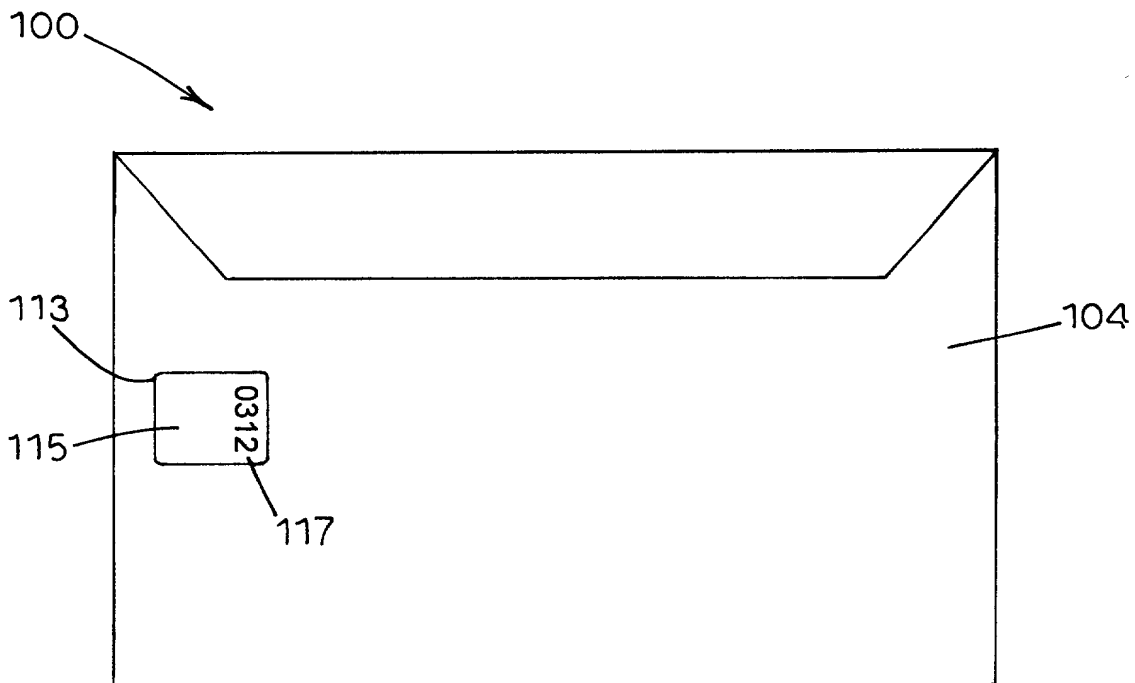


Fig. 4B